

# CERTIFICATE OF BEST PAPER AWARD

ICRA 2023: XVII. International Conference on Robotics and Autonomy  
hereby certifies that the below mentioned paper has been selected as the best paper

Trajectory Tracking of a 2-Link Mobile Manipulator Using Sliding Mode Control Method  
Abolfazl Mohammadjoo

AMSTERDAM, NETHERLANDS



MAY 04-05, 2023